

## MATH 54 - HINTS TO HOMEWORK 7

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Here are a couple of hints to Homework 7! Enjoy! :)

### SECTION 6.1: INNER PRODUCTS, LENGTHS, AND ORTHOGONALITY

**6.1.9.** Divide the vector by its length!

**6.1.21.** What they mean by the transpose definition is  $\mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v}$ . Use the facts that  $(A + B)^T = A^T + B^T$  and  $(cA)^T = cA^T$ .

**6.1.21.** Use the fact that  $\|\mathbf{w}\|^2 = \mathbf{w} \cdot \mathbf{w}$  for any  $\mathbf{w}$ , and expand the left-hand-side out using a distributive law similar to  $(a + b)(c + d) = ac + ad + bc + bd$ .

### SECTION 6.2: ORTHOGONAL SETS

Remember: A set  $\mathcal{B}$  is orthogonal if for every pair of distinct vectors  $\mathbf{u}$  and  $\mathbf{v}$ ,  $\mathbf{u} \cdot \mathbf{v} = 0$ . It is orthonormal if it is orthogonal and every vector has length 1. An orthogonal set can be made orthonormal by dividing every vector by its length.

**6.2.9.**

$$[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} \frac{\mathbf{x} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \\ \frac{\mathbf{x} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \\ \frac{\mathbf{x} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} \end{bmatrix}$$

**6.2.11, 6.2.15.** The formula for orthogonal projection of  $\mathbf{y}$  on the line spanned by  $\mathbf{u}$  is:

$$\hat{\mathbf{y}} = \left( \frac{\mathbf{y} \cdot \mathbf{u}}{\mathbf{u} \cdot \mathbf{u}} \right) \mathbf{u}$$

The distance between  $\mathbf{u}$  and  $L$  is then  $\|\mathbf{y} - \hat{\mathbf{y}}\|$

### SECTION 6.3: ORTHOGONAL PROJECTION

Here are all the basic facts that you'll need:

(1) If  $W = \text{Span} \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ , then the orthogonal projection of  $\mathbf{y}$  onto  $W$  is:

$$\hat{\mathbf{y}} = \left( \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \right) \mathbf{u}_1 + \left( \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \right) \mathbf{u}_2 + \dots + \left( \frac{\mathbf{y} \cdot \mathbf{u}_k}{\mathbf{u}_k \cdot \mathbf{u}_k} \right) \mathbf{u}_k$$

(2) Then  $\hat{\mathbf{y}}$  is in  $W$ ,  $\mathbf{y} - \hat{\mathbf{y}}$  is in  $W^\perp$  (that is, orthogonal to  $W$ ).

(3)  $\mathbf{y} = \hat{\mathbf{y}} + (\mathbf{y} - \hat{\mathbf{y}})$ , which decomposes  $\mathbf{y}$  as a sum of two vectors, one in  $W$  and the other one orthogonal to  $W$ .

(4)  $\hat{\mathbf{y}}$  is the closest point to  $\mathbf{y}$  in  $W$ .

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(5)  $\|y - \hat{y}\|$  is the smallest distance between  $\mathbf{y}$  and  $W$ .

**6.3.21.**

- (a) **T**
- (b) **T**
- (c) **F**
- (d) **T**
- (e) **T**

SECTION 6.4: THE GRAM-SCHMIDT PROCESS

Use the formula given in Theorem 11. To get an *orthonormal* basis, just divide every vector at the end by its length. At every step, it's helpful to multiply your vector by a scalar to avoid fractions. This is ok, because you'll normalize them at the end anyway!

**6.4.13.** Here's the trick: If  $A = QR$ , then  $Q^T A = Q^T QR = R$ , since  $Q^T Q = I$  (because the columns of  $Q$  are orthonormal). Hence:

$$R = Q^T A$$

SECTION 6.5: LEAST SQUARES PROBLEMS

Here's the general procedure to solve least-squares problems: To solve  $A\mathbf{x} = \mathbf{b}$  in the least-squares sense, multiply both sides by  $A^T$ , and solve the (easier) equation  $A^T A\hat{\mathbf{x}} = A^T \mathbf{b}$ . Your solution  $\hat{\mathbf{x}}$  is called the least-squares solution. The least squares error is  $\|A\hat{\mathbf{x}} - \mathbf{b}\|$ .

**6.5.13.** No! Because  $\|A\mathbf{v} - \mathbf{b}\|$  is **smaller** than  $\|A\mathbf{u} - \mathbf{b}\|$ , so  $\mathbf{u}$  **cannot** be a least-squares solution of  $A\mathbf{x} = \mathbf{b}$ , by the **definition** of a least-squares solution! (beginning of section 6.5)

**6.5.15.** Use the formula in theorem 15.

**6.5.17.**

- (a) **T**
- (b) **T**
- (c) **F**
- (d) **T**
- (e) **T**